Ch.mo Sig.r Pr.,

Le [illegible] ora, ~~[illegible]~~ il più presto che potrei, l'indicazione precisa di quel lavoro, ~~[illegible]~~ per il quale Ella ebbe a fare un richiamo di [illegible] lo Scheff... ~~Ella mi obbligherà~~

Le ~~[illegible]~~ sarei obbligato se volesse anche ~~mandarmi~~ ~~anche~~ copia di questo lo Sche... le serve in proposito, ~~e di aggiungere~~ quanto Ella credesse utile per ~~[illegible]~~ mettere in rilievo. ~~Con anche [illegible]~~

~~[illegible]~~ Le spiegherò con lettera lo scopo della mia richiesta. Colgo l'occasione di ~~[illegible]~~ rispetto di L.

$$x\left(a\frac{\partial X}{\partial x}+b\frac{\partial X}{\partial y}+c\right.$$

$$\cancel{\lambda X+\mu Y}+\nu Z$$

abc

$$\frac{B}{C}=\frac{Y'}{Z'}$$

$$Aa+Bb+Cc=0$$

$$\frac{B}{Y'}=\frac{C}{Z'}=\frac{-Aa}{bY'+cZ'}$$

$$Aa+Bb+Cc=0$$

$$\begin{vmatrix} A & X' & a \\ B & Y' & b \\ C & Z' & c \end{vmatrix}=0 \qquad \begin{cases} Aa+Bb+Cc=0 \\ A(cY'-bZ')+B(aZ'-cX')+C(bX'-aY')=0 \end{cases}$$

$$A\equiv b(bX'-aY')+c(cX'-aZ')=X'-a(aX'+bY'+cZ')$$

$$aX'+bY'+cZ'=a^2\frac{\partial X}{\partial x}+b^2\frac{\partial Y}{\partial y}+\dots+ab\left(\frac{\partial X}{\partial y}+\frac{\partial Y}{\partial x}\right)+\dots\dots=\Phi$$

$$2a\frac{\partial X}{\partial x}+b\left(\frac{\partial X}{\partial y}+\frac{\partial Y}{\partial x}\right)+c\left(\frac{\partial X}{\partial z}+\frac{\partial Z}{\partial x}\right)=\frac{\partial\Phi}{\partial a}$$

$$\begin{cases} A\equiv aX_x+bX_y+cX_z-a\left[a^2X_x+b^2Y_y+c^2Z_z+ab(X_y+Y_x)+\dots\right] \\ B\equiv aY_x+bY_y+cY_z-b\left[\;-\;-\;-\;-\;-\;\right] \\ C\equiv aZ_x+bZ_y+cZ_z-c\left[\;-\;-\;-\;\right] \end{cases}$$

$$\begin{aligned} A&\equiv L-a(aL+bM+cN) \\ B&\equiv M-b(\;-\;-\;) \\ C&\equiv N-c(\;-\;-\;) \end{aligned}$$

$$L^2+M^2+N^2-(aL+bM+cN)^2$$

$$A=\frac{L-a(aL+bM+\dots}{\sqrt{L^2+M^2+N^2-(aL\dots}}$$

$\lambda \quad \mu \quad \nu$

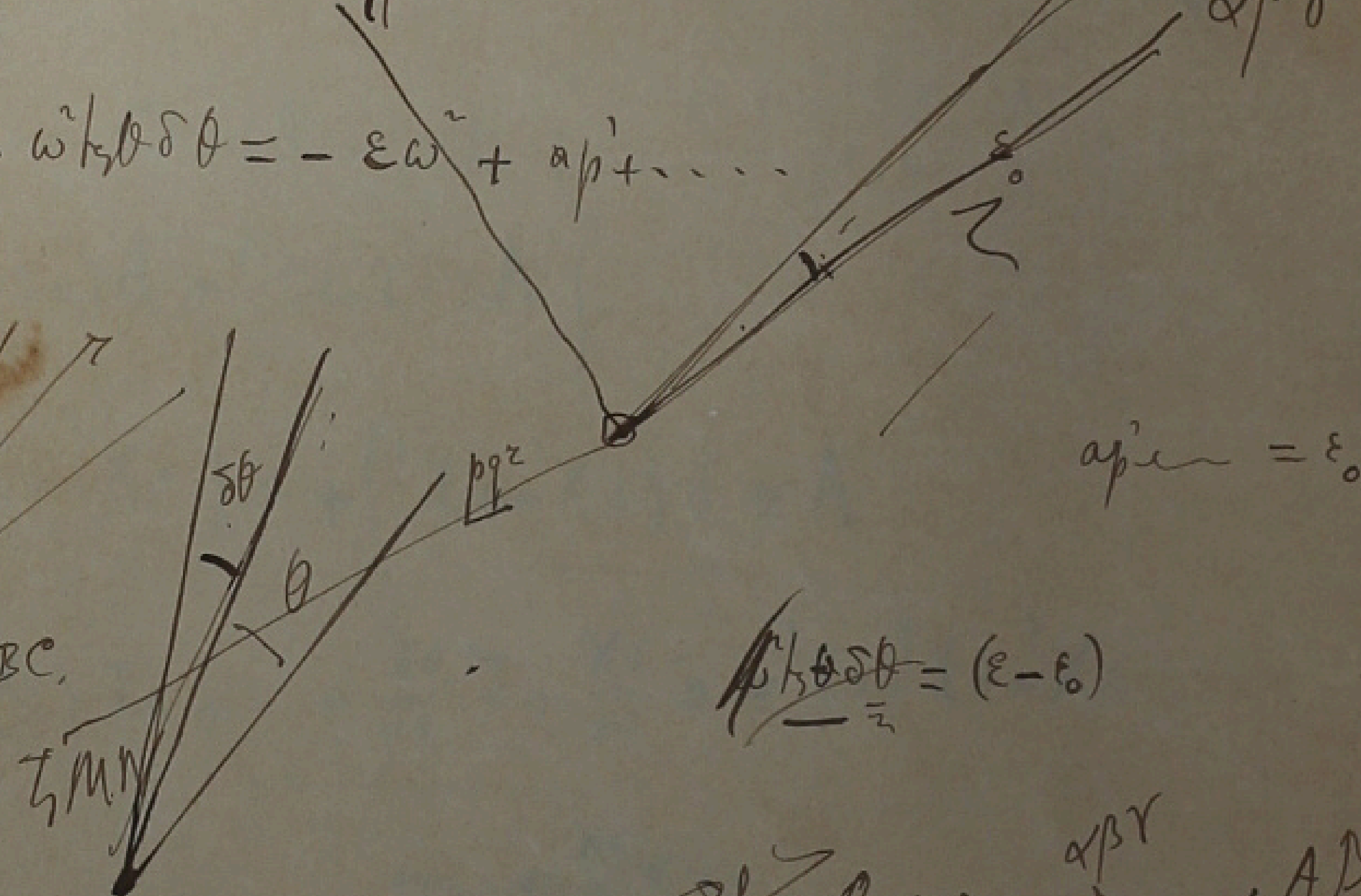
$\cancel{\cos\theta . \delta\theta = - \varepsilon \sin\theta + \varepsilon_1 \sin\theta + \frac{\lambda(ap + \ldots) + \ldots}{-\omega} \cos\theta}$

$(\lambda \cancel{\omega\theta} - \frac{p}{\omega} \cancel{tg\theta})\delta\theta + (\cancel{\ldots} + \cancel{q\ldots} + \cancel{q\lambda\ldots} \cancel{\ldots})\theta = -\varepsilon \frac{p}{\omega} \cancel{\ldots}$

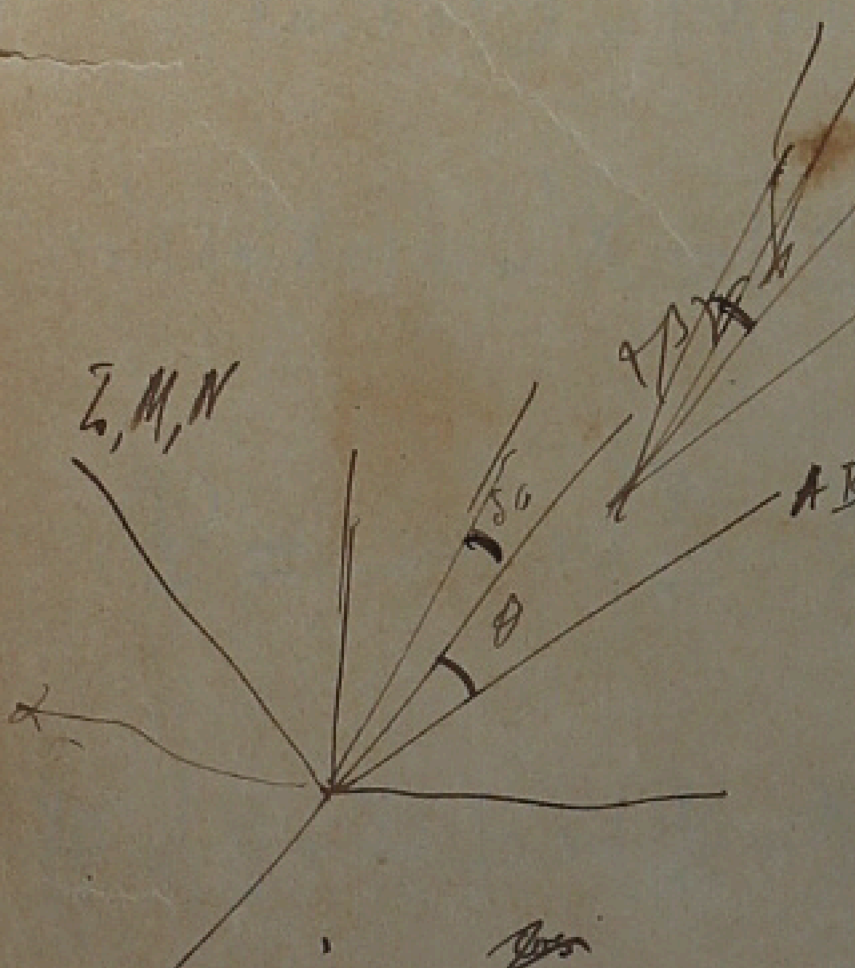
$$\left\{\begin{array}{l} (\lambda\omega - \cancel{p}\, tg\theta)\delta\theta = -\varepsilon p + ap + hq + gr \quad \lambda \\ (\mu\omega - q\, tg\theta)\delta\theta = -\varepsilon q + hp + bq + fr \quad \mu \\ \quad \nu \end{array}\right.$$

$\lambda p + \mu q$

$\alpha_1 \beta_1 \gamma_1 \omega \delta\theta = \ldots$



$-\omega^2 tg\theta\, \delta\theta = -\varepsilon\omega^2 + ap^2 + \ldots$

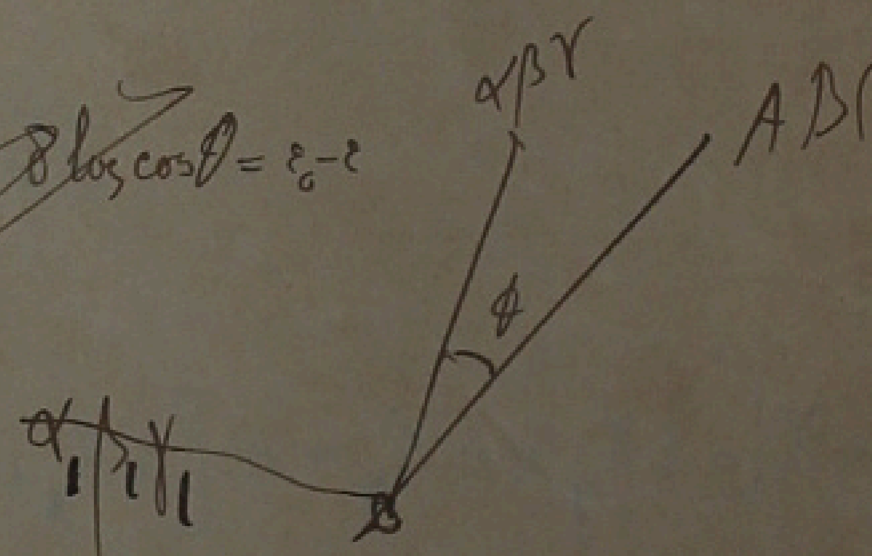


$ap^2 \ldots = \varepsilon_0 \omega^2$

$\cancel{\beta} tg\theta\, \delta\theta = (\varepsilon - \varepsilon_0)$

$\delta \log\cos\theta = \varepsilon_0 - \varepsilon$

$\frac{\sin\theta}{\cos\theta}$



$\alpha = A\cos\theta + L_1 \sin\theta$

$\alpha + \delta\alpha = A\cos(\theta + \delta\theta) + L_1 \sin(\theta + \delta\theta)$

$\cancel{\alpha} + \delta\alpha = \cancel{A}(\cos\theta - \delta\theta . \sin\theta) + L_1(\sin\theta + \delta\theta . \cos\theta)$

$\delta\alpha = (-A\sin\theta + L_1 \cos\theta)\delta\theta = \alpha_1 \delta\theta$

$\alpha_1 \delta\theta$

$\beta_1 \delta\theta$

$\gamma_1 \delta\theta$

$\frac{\delta\alpha}{\delta\varepsilon}$