

2

$$\frac{a_1}{a_2} = a_1 + \dots$$

u +

$$K Q_1 (u_1 x_1 + v_1 y_1 + w_1 z_1)$$

Ch. ...

Caro ...

Le son veni la, la pag di
 che con n uno foglio Manu. Intant
 la info che il libro del Dyck,
~~che out 1872~~ ha ~~cont~~ un supplement
 nel 1873. Bon aff a chiederli

14

al Teubner. * Per don
 domo che Elh papa la fatto *
 in rifon, ^{o ref. unti} della ~~Manu~~ di
 "Tendi Nou" di 2' Occi
 ogni ~~di~~ libri ~~anti~~
 i voli opre del Massant
 En le unti i pupi. ~~Con~~ de ~~bl~~ con un ~~no~~ ~~lo~~ ~~17~~

2, ...

923,50
 55,90
 502,00

 781,40
 17,00

 798,40

* In a m, lep
 di don il per
 del ~~leg~~ ~~del~~

Eda felt dev' in int ~~del~~ prof. E. Cera', Druk
 dell' istituto di Calisto infon, della R. Univ
 Mi con ~~1873~~ 1873

Caro ...
 ... ed sul mi ... con ...

fin

14



$$\frac{\partial \mathcal{L}}{\partial x_1} = -\frac{1}{2} K Q_0 (x_1 - x_0) (u_0 + v_0 y_0 - p_0 z_0) + \frac{1}{2} K Q_0 [x_1 (u_0 + v_0 y_0 - p_0 z_0) + y_1 (\dots) + z_1 (\dots)]$$

$$+ \frac{1}{2} K Q_0 (x_1 - x_0) (u_0 + v_0 y_0 - p_0 z_0)$$

$$+ \frac{1}{2} K Q_1 (u x_1 + v y_1 + w z_1)$$

$$\frac{\partial \mathcal{L}}{\partial x_1} = \frac{1}{2} K Q_1 (u x_1 + v y_1 + w z_1)$$

$$\frac{\partial \mathcal{L}}{\partial x_1} = \frac{1}{2} K Q [a x + h y + g z] - \frac{1}{2} K Q [(x_1 - x_0)^2 [a - \dots]] + \dots$$

$$\frac{\partial \mathcal{L}}{\partial x_1} = -\frac{1}{2} K Q (a x + h y + g z)$$

$$\frac{\partial \mathcal{L}}{\partial x_1} = -\frac{1}{2} K Q_0 (x_1 - x_0) (u_0 + v_0 y_0 - p_0 z_0) + \frac{1}{2} K Q_0 [x_1 (u_0 + \dots) + y_1 (\dots) + z_1 (\dots)]$$

$$+ \frac{1}{2} K Q_0 (x_1 - x_0) (u_0 + v_0 y_0 - p_0 z_0) + Q_1 + \int \left(\frac{\partial \mathcal{L}}{\partial x_1} dx + \frac{\partial \mathcal{L}}{\partial y_1} dy + \frac{\partial \mathcal{L}}{\partial z_1} dz \right)$$

$$\frac{\partial \mathcal{L}}{\partial x_1} = \frac{1}{2} K Q (a x + h y + g z) - \frac{1}{2} K Q (x_1 - x_0) [a - (\dots) y - (\dots) z] + \frac{1}{2} K Q x (a x + h y + g z) - K Q w$$

$$+ \frac{1}{2} K Q (x_1 - x_0) [a - (\dots) y - (\dots) z + \frac{1}{2} K Q x (a x + h y + g z) - K Q w] +$$

$$+ \frac{1}{2} K Q (y_1 - y_0) \left\{ h - \left(\frac{\partial h}{\partial z} \dots \right) z - \left(\frac{\partial h}{\partial x} - \frac{\partial a}{\partial y} \right) x + \frac{1}{2} K Q x (h x + b y - \dots) \right\}$$

$$+ \frac{1}{2} K Q (z_1 - z_0) \left\{ g - \left(\frac{\partial g}{\partial x} - \frac{\partial a}{\partial z} \right) x - \left(\frac{\partial g}{\partial y} - \frac{\partial h}{\partial z} \right) y + \frac{1}{2} K Q x (g x - \dots) \right\}$$

$$\frac{\partial \mathcal{L}}{\partial x_1} = \frac{1}{2} K Q (a x + h y + g z) + \frac{1}{2} K Q [a (x_1 - x_0) + h (y_1 - y_0) + g (z_1 - z_0)] +$$

$$+ \frac{1}{2} K Q x [x_1 (a x - \dots) + y_1 (h x - \dots) + z_1 (g x - \dots)] - K Q y + \frac{1}{2} K Q (x_1 - x_0) w$$

$$\frac{\partial \mathcal{L}}{\partial x_1} = \frac{1}{2} K Q (a x_1 + h y_1 + g z_1) + \frac{1}{2} K Q x [x_1 (a x - \dots) + y_1 (h x - \dots) + z_1 (g x - \dots)] - \frac{1}{2} K Q x_1 w +$$

$$\frac{\partial \mathcal{L}}{\partial y_1} = \frac{1}{2} K Q (h x_1 + b y_1 + f z_1) + \frac{1}{2} K Q y [x_1 (a x - \dots) + y_1 (\dots) + z_1 (\dots)] - \frac{1}{2} K Q y_1 w +$$

$$\frac{\partial \mathcal{L}}{\partial z_1} = \frac{1}{2} K Q (g x_1 - \dots) + \frac{1}{2} K Q z [x_1 (\dots) - \dots] - \frac{1}{2} K Q z_1 w +$$